

# Roundtable: What is Wrong with Automatic Mathematical Modeling

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# Challenges

- Can we establish good interfaces for all levels of the hierarchy?
- Do we need language extensions for more sophisticated problems?
- What information is required from each component?
- Is inter-language programming effective?
- Can we develop a general framework for boundary conditions?

# Outline

- 1 Interfaces
- 2 Language Issues
- 3 Boundary Conditions

# Interface Hierarchy

- Coupling
  - Semi-implicit
  - Dynamic generation of Jacobian blocks
- Domain decomposition
  - Parallelism
  - BDDC, FETI
  - Assembly

# Necessary Information

- Discretization (FIAT)
  - # of dof/dimension
  - Jet tabulation
  - Action of dual basis
  - Dof *kind*
- Functions (Section)
  - restrict/update
  - complete
- Topology (Sieve)
  - cone/support
  - closure/star
  - meet/join
- Equations (FFC)
  - Unknowns
    - Tensors
  - Knowns
    - Interpolants
    - Arbitrary functions
  - Arithmetic, Matrix arithmetic
  - Derivatives
    - div, grad, curl
    - exterior derivative/coderivative
  - Domain
    - Link mesh to equation
  - Boundary conditions
    - Operator for Dirichlet condition?
  - jump, avg

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# Language Extensions

- Optimization
  - $\min, s.t.$
- Sensitivity
- Control

# Inter-language Programming

I am now convinced that this causes more problems than it solves:

- Debugging
- Build systems
- Passing complex structures (objects)
- Top-level control



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# Dirichlet Values

- Topological boundary is marked during generation
- Cells bordering boundary are marked using `markBoundaryCells()`
- To set values:
  - 1 Loop over boundary cells
  - 2 Loop over the element closure
  - 3 For each boundary point  $i$ , apply the functional  $N_i$  to the function  $g$
- The functionals are generated with the quadrature information
- Section allocation applies Dirichlet conditions automatically
  - Values are stored in the Section
  - `restrict()` behaves normally, `update()` ignores constraints

# Boundary Condition Implementation

- Associate a transform  $\mathcal{T}$  to each sieve point
  - Could extend to the cell closure
- Constrained points also have a rotation  $\mathcal{C}$ 
  - Rotates to frame in which constrained dof are last
  - Easy to mix fields on a point
  - Applies for all values (get rotated equations)
- `update()` ignores constrained values
  - `restrict()` always retrieves all data