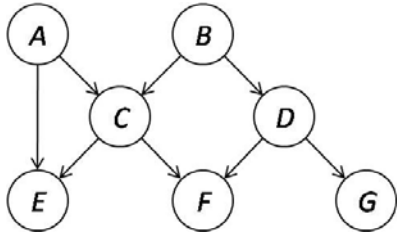


Exercises lecture 5

1. From the following Bayesian network, compute $p(A|E,F)$ in terms of known conditional probabilities:



2. a) Prove the Laplace approximation:

$$p(D|M) \approx p(D|M, \hat{\theta}_{\text{MAP}}) p(\hat{\theta}_{\text{MAP}}|M) \frac{1}{\sqrt{\det \frac{\mathbf{H}}{2\pi}}}$$

with $\mathbf{H} = -\nabla\nabla \log p(\theta|D, M)|_{\theta=\hat{\theta}_{\text{MAP}}}$.

b) What is \mathbf{H} when the posterior over θ is a multivariate Gaussian with mean $\hat{\theta}_{\text{MAP}}$ and covariance matrix Σ ?

3. The following exercise from MacKay, *Information theory, inference, and learning algorithms*

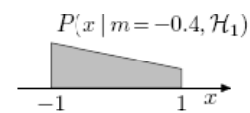
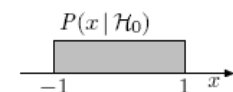
Exercise 28.1.^[3] Random variables x come independently from a probability distribution $P(x)$. According to model \mathcal{H}_0 , $P(x)$ is a uniform distribution

$$P(x|\mathcal{H}_0) = \frac{1}{2} \quad x \in (-1, 1). \quad (28.20)$$

According to model \mathcal{H}_1 , $P(x)$ is a nonuniform distribution with an unknown parameter $m \in (-1, 1)$:

$$P(x|m, \mathcal{H}_1) = \frac{1}{2}(1 + mx) \quad x \in (-1, 1). \quad (28.21)$$

Given the data $D = \{0.3, 0.5, 0.7, 0.8, 0.9\}$, what is the evidence for \mathcal{H}_0 and \mathcal{H}_1 ?



4. The following exercise from the same book:

Exercise 28.2.^[3] Datapoints (x, t) are believed to come from a straight line. The experimenter chooses x , and t is Gaussian-distributed about

$$y = w_0 + w_1 x \quad (28.22)$$

with variance σ_ν^2 . According to model \mathcal{H}_1 , the straight line is horizontal, so $w_1 = 0$. According to model \mathcal{H}_2 , w_1 is a parameter with prior distribution $\text{Normal}(0, 1)$. Both models assign a prior distribution $\text{Normal}(0, 1)$ to w_0 . Given the data set $D = \{(-8, 8), (-2, 10), (6, 11)\}$, and assuming the noise level is $\sigma_\nu = 1$, what is the evidence for each model?

