

CAAM 402/502 Spring 2013
Homework 2
Solutions

1. Problem XVII.1.1 in Lang. Let E be a vector space and let $v_1, \dots, v_n \in E$ be a basis for E . Show that any linear map $\lambda : E \rightarrow F$ into the normed vector space F is continuous.

Proof. Let us denote the norm of F by $\|\cdot\|_F$. We also equip the finite dimensional vector space E with the norm $\|\cdot\|_\infty$ defined in terms of the basis $\{v_1, \dots, v_n\}$ as follows. Given $x \in E$, let $x = \sum_{i=1}^n \alpha_i v_i$ where the scalars α_i are uniquely determined by x . Then $\|x\|_\infty = \max_i |\alpha_i|$. We break the proof into 2 claims.

Claim 1: The linear map $\lambda : (E, \|\cdot\|_\infty) \rightarrow (F, \|\cdot\|_F)$ is continuous. Proof: In virtue of the result found in Lang page 455, we may equivalently prove that λ is bounded. Let $x \in E$ be arbitrary. There exist scalars $\{\alpha_1, \dots, \alpha_n\}$ uniquely determined by x such that $x = \sum_{i=1}^n \alpha_i v_i$. Then

$$\|\lambda(x)\|_F = \left\| \sum_{i=1}^n \alpha_i \lambda(v_i) \right\|_F \leq \sum_{i=1}^n |\alpha_i| \|\lambda(v_i)\|_F \leq \left(\max_i |\alpha_i| \right) \sum_{i=1}^n \|\lambda(v_i)\|_F = C \|x\|_\infty$$

where $C = \sum_{i=1}^n \|\lambda(v_i)\|_F$ is clearly independent of x . Hence λ is bounded.

Claim 2: Let $\|\cdot\|_E$ be any norm on E . Then the linear map $\lambda : (E, \|\cdot\|_E) \rightarrow (F, \|\cdot\|_F)$ is continuous. Proof: Again we show boundedness. We use Theorem 4.3 (Lang page 145) on the equivalence of norms for finite-dimensional spaces. Then there exists a constant $K > 0$ such that

$$\|x\|_\infty \leq K \|x\|_E, \quad \text{for all } x \in E$$

Then, from Claim 1, we have that,

$$\|\lambda(x)\|_F \leq C \|x\|_\infty \leq CK \|x\|_E, \quad \text{for all } x \in E$$

which makes λ a bounded map. □

2. Let $f : [-1, 1] \rightarrow \mathbb{R}$ be defined as

$$f(x) = \begin{cases} 3x^2, & \text{if } x \in \mathbb{Q} \cap [-1, 1]; \\ 0, & \text{otherwise.} \end{cases}$$

Show that f is not differentiable at any point in $[-1, 1]$ except for $x = 0$.

Proof. Since differentiability implies continuity, then f cannot be differentiable at points where it is not continuous. Now we show that f is differentiable at $x = 0$ and that $f'(0) = 0$. Consider $h \neq 0$ and

$$0 \leq \left| \frac{f(h) - f(0)}{h} \right| = \frac{f(h)}{|h|} \leq \frac{3h^2}{|h|} = 3|h|.$$

So in the limit as $h \rightarrow 0$, we obtain that $f'(0) = 0$. □

3. Problem XVII.1.4 in Lang. Let E, F and G be normed vector spaces. A map

$$\lambda : E \times F \rightarrow G$$

is said to be *bilinear* if it satisfies the conditions,

$$\begin{aligned}\lambda(v, w_1 + w_2) &= \lambda(v, w_1) + \lambda(v, w_2) \\ \lambda(v_1 + v_2, w) &= \lambda(v_1, w) + \lambda(v_2, w) \\ \lambda(cv, w) &= c\lambda(v, w) = \lambda(v, cw)\end{aligned}$$

for all $v, v_i \in E, w, w_i \in F$ and $c \in \mathbb{R}$

- (a) Show that a bilinear map λ is continuous if and only if there exists ($C > 0$) such that for all $(v, w) \in E \times F$ we have

$$|\lambda(v, w)| \leq C|v||w|$$

Proof. “ \Rightarrow ”, λ is continuous $\Rightarrow \lambda$ is continuous at $(0, 0)$. This means that there exist $\delta_1, \delta_2 > 0$ such that

$$|v_i| \leq \delta_1, |w_i| \leq \delta_2 \Rightarrow |\lambda(v_i, w_i) - \lambda(0, 0)| \leq 1$$

We have $\lambda(0, 0) = 0$ from third property of bilinear map. Hence

$$|v_i| \leq \delta_1, |w_i| \leq \delta_2 \Rightarrow |\lambda(v_i, w_i)| \leq 1$$

Consider for any $v \in E, w \in F, v_i = \frac{v}{|v|}\delta_1$ and $w_i = \frac{w}{|w|}\delta_2$. Clearly $|v_i| = \delta_1$ and $|w_i| = \delta_2$.

Therefore we have,

$$\lambda\left(\frac{v}{|v|}\delta_1, \frac{w}{|w|}\delta_2\right) \leq 1 \Rightarrow \frac{\delta_1}{|v|} \frac{\delta_2}{|w|} |\lambda(v, w)| \leq 1 \Rightarrow |\lambda(v, w)| \leq \frac{1}{\delta_1\delta_2} |v||w| \Rightarrow |\lambda(v, w)| \leq C|v||w|$$

with $C = \frac{1}{\delta_1\delta_2}$.

“ \Leftarrow ” Assume that there exists $C > 0$ such that $|\lambda(v, w)| \leq C|v||w|$ for all $(v, w) \in E \times F$. For any $\epsilon > 0$ and $(v_i, w_i) \in E \times F$, pick $\delta = \min\left(1, \frac{\epsilon}{C(1 + |v_i| + |w_i|)}\right)$

$$\begin{aligned}|\lambda(v, w) - \lambda(v_i, w_i)| &= |\lambda(v - v_i, w_i) + \lambda(v - v_i, w - w_i) + \lambda(v_i, w - w_i)| \\ &\leq |\lambda(v - v_i, w_i)| + |\lambda(v - v_i, w - w_i)| + |\lambda(v_i, w - w_i)| \\ &\leq C|v - v_i||w_i| + C|v - v_i||w - w_i| + C|v_i||w - w_i| \\ &< C\delta|w_i| + C\delta^2 + C\delta|v_i| \quad \text{for } |v - v_i| < \delta, |w - w_i| < \delta \\ &< \epsilon\end{aligned}$$

Hence λ is continuous at every $(v_i, w_i) \in E \times F$ □

- (b) Let $v \in E$ be fixed. Show that if λ is continuous, then the map $\lambda_v : F \rightarrow G$ given by $w \rightarrow \lambda(v, w)$ is a continuous linear map.

Proof. Let $\alpha, \beta \in \mathbb{R}$ and $w_1, w_2 \in F$.

$$\lambda_v(\alpha w_1 + \beta w_2) = \lambda(v, \alpha w_1 + \beta w_2) = \lambda(v, \alpha w_1) + \lambda(v, \beta w_2) = \alpha\lambda(v, w_1) + \beta\lambda(v, w_2) = \alpha\lambda_v(w_1) + \beta\lambda_v(w_2)$$

Hence λ_v is linear.

$$|\lambda_v(w)| = |\lambda(v, w)| \leq C|v||w| = C_v|w| \Rightarrow |\lambda_v(w)| \leq C_v|w| \quad C_v = C|v|$$

Hence λ_v is bounded and linear. Hence λ_v is a continuous linear map. □

4. Let S be an open and connected set in \mathbb{R}^n , and consider the differentiable function $f : S \rightarrow \mathbb{R}^m$ with derivative $f'(c) = 0$ (the linear map zero), for all $c \in S$. Prove that f is constant. **Hint:** Use the result of Problem 1 below, which says that S is polygonally connected.

Proof. Fix $a \in S$ and let $x \in S$. Since S is open and connected, it is polygonally connected (Problem 1 for 502). Thus, there exist points $x_0 = a, x_1, \dots, x_k = x$ such that $L(x_{j-1}, x_j)$ (line segment between two points) is in S for all $j = 1, \dots, k$.

By the fundamental theorem of calculus we have that

$$f(x_j) - f(x_{j-1}) = \int_0^1 f'(tx_j + (1-t)x_{j-1})dt (x_j - x_{j-1}) = 0$$

for $j = 1, \dots, k$. Summing over j we get

$$0 = \sum_{j=1}^k (f(x_j) - f(x_{j-1})) = f(x) - f(a).$$

Hence, $f(x) = f(a)$ for all $x \in S$, that is, f is constant. □

ADDITIONAL PROBLEMS FOR CAAM 502

1. Let S be an open and connected set in \mathbb{R}^n . Prove that S is polygonally connected, ie., any two points x and y in S can be joined by a polygonal line.

Proof. Since S is connected, then the only set two sets in S that are both open and closed (with respect to S) are the whole set S and the empty set \emptyset . Assume that S is not empty and let $a \in S$. Let $C \subset S$ denote the set of all the points in S that are polygonally connected to a . This set C is clearly nonempty since a is polygonally to itself. Now we claim that C is both open and closed with respect to S .

We proceed to prove openness first. Let $x \in C \subset S$. Since S is open in \mathbb{R}^n , then there exists $r > 0$ such that $B_r(x) \subset S$. Let $y \in B_r(x)$ be arbitrary. Notice that the line segment from x to y stays within $B_r(x) \subset S$ (by convexity). Now since $x \in C$ there is a polygonal line in S from a to x . We simply join this line with the line segment from x to y to obtain the desired polygonal line from a to y . Hence we have that $B_r(x) \subset C$ which implies that C is open in S .

Finally we proceed to show that C is closed with respect to S or equivalent that the complement $S \setminus C$ is open. Take $x \in S \setminus C$ arbitrary (no polygonal line from a to x). Since S is open in \mathbb{R}^n , then there exists $r > 0$ such that $B_r(x) \subset S$. No point y in the ball $B_r(x)$ can belong to C , otherwise (like before) we could join a line segment to connected to the center of the ball which is x , and this cannot happen since $x \notin C$. Hence $B_r(x) \subset S \setminus C$ which makes $S \setminus C$ open in S .

Since a was chosen arbitrarily in S , then we conclude that S is polygonally connected. \square

2. Let E and F be normed vector spaces and denote by $L^2(E, F)$ the space of continuous bilinear maps of $E \times E \rightarrow F$. Let $\lambda \in L^2(E, F)$ and define $\|\lambda\|$ to be the greatest lower bound of all numbers $C > 0$ such that

$$\|\lambda(v_1, v_2)\|_F \leq C \|v_1\|_E \|v_2\|_E \quad \forall v_1, v_2 \in E$$

Show that $\|\lambda\|$ is a norm in $\lambda \in L^2(E, F)$ and verify that its definition is equivalent to

$$\|\lambda\| = \sup_{v_1, v_2 \neq 0} \frac{\|\lambda(v_1, v_2)\|_F}{\|v_1\|_E \|v_2\|_E}$$

Proof. First we verify the equivalence of definitions. This follows from the fact that the greatest lower bound of all C 's that satisfy the above inequality coincides with the least upper bound of all C 's that do not satisfy the same inequality. Now we check the axioms of a norm.

N1. $\|\lambda\| \geq 0$ and $\|\lambda\| = 0$ iff $\lambda = 0$

$\|\lambda\|$ is the greatest lower bound of all C 's that satisfy the above inequality. Hence

$$\frac{\|\lambda(v_1, v_2)\|_F}{\|v_1\|_E \|v_2\|_E} \leq \|\lambda\|$$

$\|\cdot\|_F$ is a norm, hence $\|\lambda(v_1, v_2)\|_F \geq 0 \Rightarrow \|\lambda\| \geq 0$.

If $\|\lambda\| = 0 \Rightarrow \|\lambda(v_1, v_2)\|_F = 0, \forall v_1, v_2 \in E \Rightarrow \lambda(v_1, v_2) = 0, \forall v_1, v_2 \in E$. Hence $\lambda = 0$

N2. For any $\alpha \in \mathbb{R}$ $\|\alpha\lambda\| = |\alpha| \|\lambda\|$

For any $C > 0$ satisfying the given inequality, we have

$$\|\alpha\lambda(v_1, v_2)\|_F = |\alpha| \|\lambda(v_1, v_2)\|_F \leq |\alpha| C \|v_1\|_E \|v_2\|_E$$

If $\|\lambda\|$ is the greatest lower bound of all possible numbers C , $|\alpha| \|\lambda\|$ is the greatest lower bound of all possible numbers $|\alpha| C$. Hence $\|\alpha\lambda\| = |\alpha| \|\lambda\|$

N3. $\|\lambda_1 + \lambda_2\| \leq \|\lambda_1\| + \|\lambda_2\|$ for any $\lambda_1, \lambda_2 \in L^2(E, F)$

We have

$$\|\lambda_1(v_1, v_2)\|_F \leq \|\lambda_1\| \|v_1\|_E \|v_2\|_E$$

and

$$\|\lambda_2(v_1, v_2)\|_F \leq \|\lambda_2\| \|v_1\|_E \|v_2\|_E$$

by adding the above two inequalities,

$$\|\lambda_1(v_1, v_2)\|_F + \|\lambda_2(v_1, v_2)\|_F \leq \|\lambda_1\| \|v_1\|_E \|v_2\|_E + \|\lambda_2\| \|v_1\|_E \|v_2\|_E = (\|\lambda_1\| + \|\lambda_2\|) \|v_1\|_E \|v_2\|_E$$

From the norm property of $\|\cdot\|_F$ and the above inequality,

$$\|(\lambda_1 + \lambda_2)(v_1, v_2)\|_F \leq \|\lambda_1(v_1, v_2)\|_F + \|\lambda_2(v_1, v_2)\|_F \leq (\|\lambda_1\| + \|\lambda_2\|) \|v_1\|_E \|v_2\|_E$$

From the definition, $\|\lambda_1 + \lambda_2\| \leq C = \|\lambda_1\| + \|\lambda_2\|$.

□

3. Let E and F be normed vector spaces and $\lambda \in L(E, L(E, F))$. Let also $f_\lambda \in L^2(E, F)$ be the continuous bilinear map defined by

$$f_\lambda(v_1, v_2) = [\lambda(v_1)](v_2) \quad \forall v_1, v_2 \in E$$

Prove that $\|f_\lambda\| = \|\lambda\|$

Proof.

$$\|\lambda\| = \sup_{v_1 \neq 0} \frac{\|\lambda(v_1)\|_{L(E, F)}}{\|v_1\|_E} = \sup_{v_1 \neq 0} \frac{\sup_{v_2 \neq 0} \frac{\|[\lambda(v_1)](v_2)\|_F}{\|v_2\|_E}}{\|v_1\|_E} = \sup_{v_1, v_2 \neq 0} \frac{\|[\lambda(v_1)](v_2)\|_F}{\|v_2\|_E \|v_1\|_E} = \|f_\lambda\|$$

□