

Next section: numerical linear algebra.

Assumes basic linear algebra knowledge, but focuses on numerical tools. Matrix factorizations.

Suppose  $A \in \mathbb{R}^{m \times n}$  is a matrix.  
 $x \in \mathbb{R}^n$

Norms: norms on vectors  $\|x\|_p = \left( \sum_{i=1}^n |x_i|^p \right)^{1/p}$   
Common choices for  $p = 1, 2, \infty$   
w/  $\|x\|_\infty = \max_i |x_i|$

Norms on matrices: definitions

- ①  $\|A\| \geq 0$  &  $\|A\| = 0 \Leftrightarrow A = 0$
- ②  $\|\alpha A\| = |\alpha| \|A\|$
- ③  $\|A+B\| \leq \|A\| + \|B\|$

Induced norms on matrices:

$$\|A\|_p = \max_{x \neq 0} \frac{\|Ax\|_p}{\|x\|_p}, \quad p = 1, 2, \infty \text{ common}$$

$$\|A\|_1 = \max_j \sum_{i=1}^m |A_{ij}|$$

$$\|A\|_\infty = \max_i \sum_{j=1}^n |A_{ij}|$$

$$\|A\|_2 = \max_i |\lambda_i|, \quad \lambda_i = \text{eigenvalue of } A, \quad m=n \text{ (for square matrices)}$$

Non-induced norms:  $\|A\|_F^2 = \sum_i \sum_j |A_{ij}|^2$

## Cauchy-Schwarz inequality:

assuming  $B \neq 0$

$$\|AB\| = \max_{x \neq 0} \frac{\|ABx\|}{\|x\|} = \max_{x \neq 0} \frac{\|ABx\|}{\|Bx\|} \frac{\|Bx\|}{\|x\|}$$

$$\begin{aligned} y = Bx &\leq \max_{y \neq 0} \frac{\|Ay\|}{\|y\|} \max_{x \neq 0} \frac{\|Bx\|}{\|x\|} \\ &\leq \|A\| \|B\| \end{aligned}$$

$\dagger$  holds for Frobenius norm.

## Vector space settings: $U \subset \mathbb{C}^n$

$U$  is a subspace if  $u, v \in U \Rightarrow \alpha u + \beta v \in U$   
 $\alpha, \beta = \text{scalars}$

$$R(A) = \text{Ran}(A) = \{Ax : x \in \mathbb{C}^n\}$$

$$N(A) = \text{Ker}(A) = \{x \in \mathbb{C}^n : Ax = 0\}$$

Rank of  $A = \dim(R(A)) = \#$  of basis vectors  
needed to represent  $R(A)$

Some Matrix  $A$  is nonsingular if

(1)  $R(A) = \mathbb{C}^n \Leftrightarrow \text{rank}(A) = n$

(2)  $N(A) = \{0\}$

If  $A$  is square  $\begin{cases} \text{(3)} & A \text{ has no zero eigenvalues} \\ \text{(4)} & A^{-1} \text{ exists \& is well defined} \end{cases}$

(conj) transpose:  $x^* = \bar{x}^T$ .  $A^* = \bar{A}^T$

Orthogonality:  $x, y \in \mathbb{C}^n$  are orthogonal if  
 $x^* y = 0 \Leftrightarrow x \perp y$

Subspaces  $U, V$  are orthog. if  $u \perp v$  for all  $u \in U$   
 $v \in V$

Note:  $y \in R(A)$ ,  $x \in N(A^*)$   
 $y = Az$  for some  $z$   $A^* x = 0$

$$x^* y = x^* A z = (A^* x)^* z = 0$$

Fundamental Thm of linear algebra: for  $A \in \mathbb{C}^{m \times n}$

$$R(A) \perp N(A^*)$$

$$R(A^*) \perp N(A)$$

$$\mathbb{C}^m = R(A) \oplus N(A^*)$$

$$\mathbb{C}^n = R(A^*) \oplus N(A)$$

QR factorization  $\Rightarrow A = QR$

$m \times n$        $m \times m$      $m \times n$   
 $m \times n$      $n \times n$   
 ↓            ↓  
 "unitary"    upper  
 $Q^*Q = I$     triangular

Projector and reflector matrices.

$P \in \mathbb{C}^{n \times n}$  is a projector if  $P^2 = P$  (idempotent)

$$P^2 x \in R(P)$$

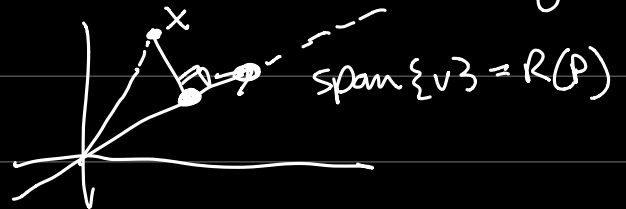
$P = P^*$   $\Rightarrow$  orthogonal projector,

$$x - Px \perp R(P)$$

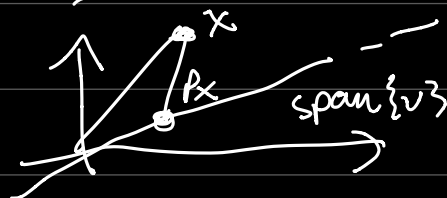
(by FTLA)  $\Rightarrow x - Px \in N(P^*) = N(P)$

Ex: Given  $v \in \mathbb{C}^n$ ,  $P = \frac{vv^*}{v^*v}$  = orthogonal projector

$$Px = v \frac{(v^*x)}{(v^*v)}$$



Ex:  $P = \frac{uu^*}{v^*u}$



Complementary projectors: If  $P^2 = P$ ,  $Q = I - P$

is a projector onto  $N(P) \Rightarrow PQ = 0$

$$(PQ = P(I - P) = P - P^2 = 0)$$

$$R(Q) = N(P)$$

$$R(P) = N(Q)$$

Householder reflectors: built from projectors  
 + complementary projectors

$$v \in \mathbb{C}^n$$

$$H(v) = I - 2P, \quad P = \frac{vv^*}{v^*v}$$

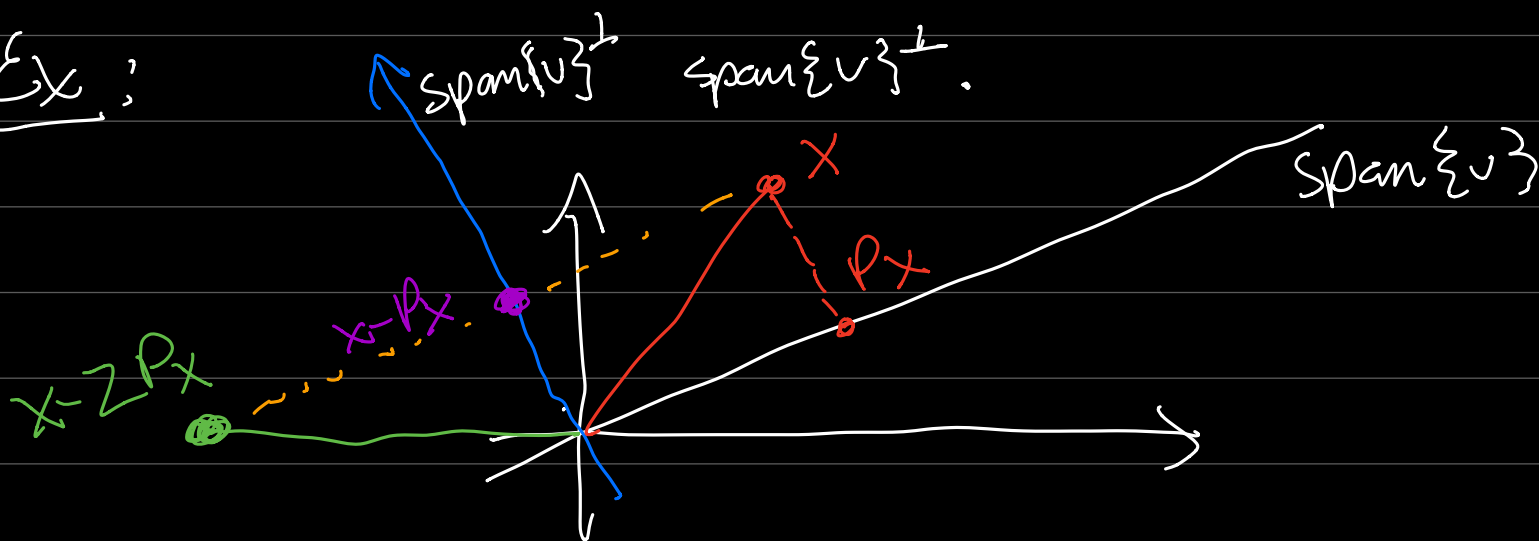
$$H(v) \text{ Hermitian \& unitary } H(v)^* H(v) = I$$

$$H(v) H(v)^* = I$$

$$H(v)x = x - 2Px$$

reflection of  $x$  over the  $n-1$   
 dimension hyperplane defined by

Ex:



Unitary matrix  $U^*U = I$

$$\Rightarrow \|Ux\|^2 = (Ux)^* Ux = x^* U^* Ux = x^* x = \|x\|^2$$

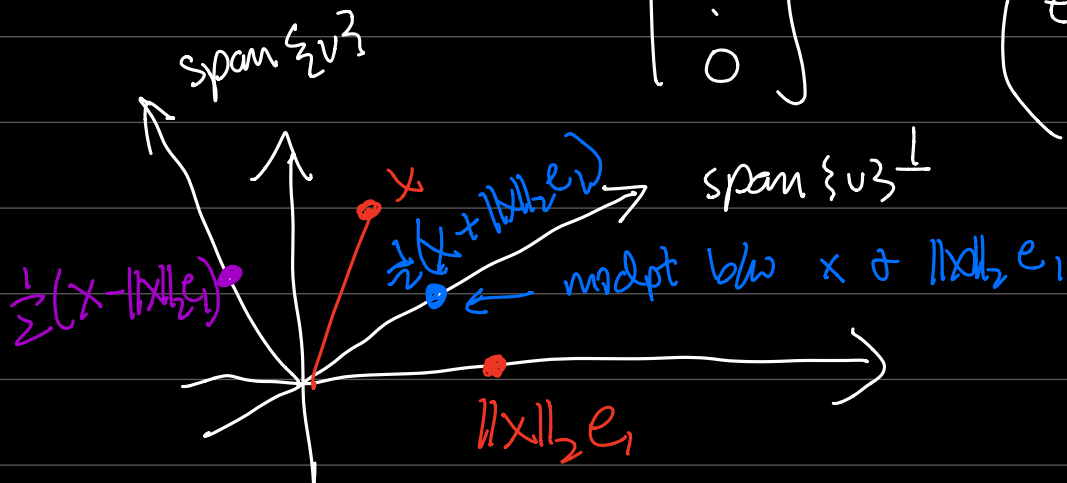
$\Rightarrow H(v)x$  doesn't change norm.

Use  $H(v)$  to zero out entries of a vector using unitary matrix operations

Goal: given  $x$ , find  $v$  st.

$$H(v)x = \begin{bmatrix} \|x\|_2 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \|x\|_2 e_1$$

$$\left( e_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right)$$



$$v = x - \|x\|_2 e_1 \Rightarrow H(v)x = \|x\|_2 e_1$$