

Last week: QR factorization.

Solving least squares: $\min \|Ax - b\|_2^2$

$$\Rightarrow A^T A x = A^T b$$

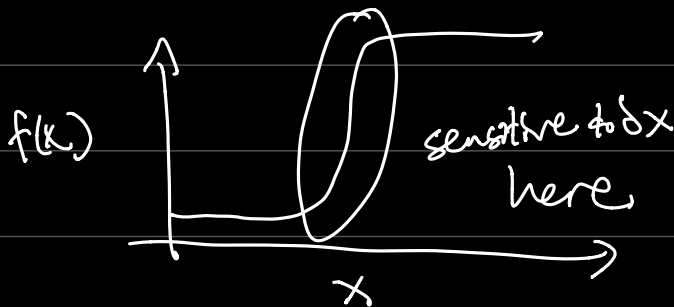
$$\Rightarrow R x = Q^T b$$

No need to construct $A^T A$ if using QR.

Conditioning: measuring sensitivity w.r.t. small perturbations.

well-conditioned =

$$f(x) - f(x + \delta x) \Rightarrow \text{small if } \delta x \text{ is small}$$



Def: Let $f: X \rightarrow Y$ be our algorithm or numerical method or problem.

① A problem is well conditioned if small changes in x lead to small changes in $f(x)$.

② A problem is ill conditioned if otherwise: small changes in x can lead to large changes in $f(x)$.

③ Define $\delta f = f(x + \delta x) - f(x)$

Absolute cond. num: $\tilde{\kappa} = \limsup_{\delta \rightarrow 0} \frac{\|\delta f\|}{\|\delta x\|}$

④ Relative cond. num. :

$$\kappa = \limsup_{\delta \rightarrow 0} \frac{\| \delta f \| / \| f \|}{\| \delta x \| / \| x \|}$$

$f(Ax) = Ax \Rightarrow$ Suppose $Ax = b$.

$$(A + \delta A)(x + \delta x) = b$$

$$\underbrace{Ax}_b + \underbrace{\delta Ax + A\delta x}_{\text{"}\delta b\text{"}} + \underbrace{\delta A\delta x}_{\text{assume } \approx 0}$$

$$\delta Ax + A\delta x = 0$$

$$\Rightarrow A\delta x = -\delta Ax$$

$$\delta x = -A^{-1} \delta Ax$$

$$\Rightarrow \frac{\| \delta x \|}{\| x \|} \leq \underbrace{\| A \| \| A^{-1} \|}_{\text{Matrix cond. num } \kappa(A)} \frac{\| \delta A \|}{\| A \|} \Rightarrow$$

relative sensitivity of x
w.r.t rel. sensitivity of A
depends on $\| A^{-1} \| \| A \|$

Ex : $Ax = b \Rightarrow$ examine $A(x + \delta x) = b + \delta b$

$$Ax + A\delta x = b + \delta b$$

$$A\delta x = \delta b \Rightarrow \frac{\| \delta x \|}{\| x \|} \leq \frac{\| A^{-1} \| \| \delta b \|}{\| x \|} \frac{\| b \|}{\| b \|}$$

$$\boxed{\frac{\| \delta x \|}{\| x \|}} \leq \frac{\| A^{-1} \| \| \delta b \|}{\| x \| \| b \|} \| Ax \| \leq \underbrace{\| A \| \| A^{-1} \|}_{\kappa(A)} \boxed{\frac{\| \delta b \|}{\| b \|}}$$

$\kappa(A)$ measures how close A is to being singular. If $\kappa(A) = 1$, as far away from singular as possible. If $\kappa(A) \gg 1 \Rightarrow A$ can become singular under a small perturbation.

\rightarrow Vandermonde matrix \rightarrow large cond. num.

\rightarrow Hilbert matrix: $\begin{bmatrix} \frac{1}{i+j-1} & \rightarrow \\ \vdots & \vdots \\ \vdots & \vdots \end{bmatrix} \rightarrow$ worst cond. num. of many matrices

$\rightarrow A^T A$ normal matrix. If A square

$$\kappa(A) = \|A\| \|A^{-1}\|$$

$$\begin{aligned} \kappa(A^T A) &= \|A^T A\| \|(A^T A)^{-1}\| \leq \|A\|^2 \|A^{-T}\| \|A^{-1}\| \\ &\leq \|A\|^2 \|A^{-1}\|^2 \\ &= \kappa(A)^2 \end{aligned}$$

\rightarrow How to generalize to rectangular matrices?
 \hookrightarrow singular value decomposition (SVD)

- SVD:
- ① generalize cond. numbers
 - ② generalize solutions of least squares to singular A
 - ③ "Rolls-Royce" of matrix factorizations
 \Rightarrow FTLA, norms, inverses

Given A :

Derive based on eigenvalues/vectors of A^*A and $AA^* \Rightarrow$ Hermitian & positive semi-definite.

$$\underbrace{x^* A^* A x}_{(Ax)^*(Ax)} \geq 0 = \|Ax\|^2$$

Recall: $H \in \mathbb{C}^{n \times n}$
 If $H = H^*$ & $x^* H x \geq 0 \quad \forall x \in \mathbb{C}^n$
 Let $H v_j = \lambda_j v_j \Rightarrow (\lambda_j, v_j) =$ eigenvalues & eigenvectors

① $\{v_j\}$ form an orthogonal (orthonormal) basis for \mathbb{C}^n

② $H = H^* \Rightarrow \lambda_j \in \mathbb{R}$

③ $x^* H x \geq 0 \Rightarrow \lambda_j \geq 0$

PF: ① For λ_j distinct λ_k

$$H v_j = \lambda_j v_j$$

$$H v_k = \lambda_k v_k$$

$$\underbrace{v_k^* H v_j}_{v_k^* H v_j \text{ by } H = H^*} = \lambda_j v_j^* v_k \Rightarrow \underbrace{(\lambda_j - \lambda_k)}_{\text{distinct} \Rightarrow \neq 0} (v_j^* v_k) = 0$$

$$\underbrace{v_j^* H v_k}_{v_k^* H v_j \text{ by } H = H^*} = \lambda_k v_j^* v_k$$

$$\Rightarrow v_j^* v_k = 0$$

$$\textcircled{2} \quad H = H^*, \quad \lambda_j \in \mathbb{R}, \quad v_j^* H v_j = \lambda_j v_j^* v_j$$

$$\textcircled{1} \quad v_j^* (H v_j) = \lambda_j (v_j^* v_j)$$

$$\textcircled{2} \quad (H v_j)^* v_j = \overline{\lambda_j} (v_j^* v_j)$$

$$\textcircled{1} - \textcircled{2} \Rightarrow 0 = (\lambda_j - \overline{\lambda_j}) \underbrace{(v_j^* v_j)}_{\neq 0}$$

$$\Rightarrow \lambda_j \in \mathbb{R}.$$

$$\textcircled{3} \quad \underbrace{v_j^* H v_j}_{\geq 0} = \lambda_j \underbrace{(v_j^* v_j)}_{\geq 0} \Rightarrow \lambda_j \geq 0$$

$A^* A + A A^*$ sym., pos. semi-det.

SVD: $A = U \Sigma V^*$, U, V related to $A A^*$
 $A^* A$

$U, V =$ unitary, $\Sigma =$ diagonal ^{real +} w/ pos. entries.

SVD derivation: Let $A \in \mathbb{C}^{m \times n}$, full rank, suppose $m \geq n$.

① Let v_1, \dots, v_n are eigenvectors of $A^* A$.

$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n \geq 0.$$

$$\textcircled{2} \quad \text{let } \sigma_j = \|A v_j\| = \sqrt{(A v_j)^* (A v_j)} \\ = \sqrt{v_j^* A^* A v_j} = \sqrt{\lambda_j}$$

③ $u_j = \frac{1}{\sigma_j} A v_j$. Note $u_j^* u_k = \frac{1}{\sigma_j \sigma_k} (A v_j)^* (A v_k) = \frac{1}{\sigma_j \sigma_k} v_j^* A^* A v_k = \begin{cases} 1 & \text{if } j=k \\ 0 & \text{if } j \neq k \end{cases}$

$u_j = \frac{1}{\sigma_j} A v_j$ for $j = 1, \dots, n$

$$\begin{bmatrix} | & & | \\ u_1 & \dots & u_n \\ | & & | \end{bmatrix} = \begin{bmatrix} | & & | \\ \frac{1}{\sigma_1} A v_1 & \frac{1}{\sigma_2} A v_2 & \dots & \frac{1}{\sigma_n} A v_n \\ | & & | \end{bmatrix}$$

$$U = \begin{bmatrix} | & & | \\ A v_1 & \dots & A v_n \\ | & & | \end{bmatrix} \begin{bmatrix} \frac{1}{\sigma_1} & & \\ & \dots & \\ & & \frac{1}{\sigma_n} \end{bmatrix} = A \begin{bmatrix} | & & | \\ v_1 & \dots & v_n \\ | & & | \end{bmatrix} \Sigma^{-1}$$

$$U = A V \Sigma^{-1}$$

$\Rightarrow U \Sigma V^* = A$ for $A \in \mathbb{R}^{m \times n}$ $m \geq n$ & full rank.
 "reduced" SVD