

Last time: LU factorization w/ partial pivoting
 $PA = LU \rightarrow$ needed properties of unit elementary lower triangular matrices.

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \text{ fails w/out pivoting}$$

numerically

How stable is pivoting?

$$A = LU$$

$$A + \delta A = \hat{L} \hat{U}$$

with floating point roundoff

$$\omega \left(\frac{\|\delta A\|}{\|\hat{L}\| \|\hat{U}\|} \right) = O(\epsilon_{mach})$$

$$\|\delta A\| = O(\epsilon_{mach}) \text{ if } \|\hat{L}\|, \|\hat{U}\| = O(1)$$

Note $|L_{ij}| \leq 1$ b/c $l_{jk} = \frac{u_{jk}}{u_{kk}}$
 $\delta u_{kk} \geq u_{jk} \forall j$
 $\Rightarrow \|\hat{L}\| = O(1)$ by pivoting.

$$\Rightarrow \frac{\|\delta A\|}{\|A\|} \leq \frac{\|\delta A\|}{\|A\|} \frac{\|\hat{U}\|}{\|\hat{U}\|} \underbrace{\frac{\|\hat{L}\|}{\|\hat{L}\|}}_{\leq C} \leq C \frac{\|\delta A\|}{\|\hat{U}\| \|\hat{L}\|} \frac{\|\hat{U}\|}{\|A\|}$$

$$\leq C O(\epsilon_{mach}) \frac{\|\hat{U}\|}{\|A\|}$$

Can est. $\frac{\|\hat{U}\|}{\|A\|} \leq \text{Const} \times g \quad w/g = \frac{\max |u_{jk}|}{\max |a_{jk}|}$

$$\frac{\|SA\|}{\|A\|} \leq f O(\epsilon_{mach}), \quad f = \text{amplification factor.}$$

Kahan matrix $\Rightarrow f \leq 2^{n-1}$ w/ $A \in \mathbb{R}^{n \times n}$

$$A = \begin{bmatrix} 1 & & & 1 \\ -1 & 1 & & 1 \\ -1 & -1 & 1 & 1 \\ -1 & -1 & -1 & 1 \\ -1 & -1 & -1 & 1 \end{bmatrix}$$

add row 1 to row 2
add row 1 to row 3

1st column of U

$$\Rightarrow \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & -1 \\ 0 & -1 \\ 0 & -1 \end{bmatrix} \xrightarrow{\text{2nd column of } U} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 2 \\ 0 & 2 \\ 0 & 2 \end{bmatrix} \xrightarrow{\text{2nd column of } U} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 4 \\ 0 & 0 & -1 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & & & 1 \\ & 1 & & 2 \\ & & 1 & 4 \\ & & & \ddots \\ & & & & z^{n+1} \end{bmatrix} = U$$

QR, SVD exist for any matrix ($\mathbb{R}^{m \times n}$)

LU exists for any non-singular square A

Cholesky or LDL^T

$\| \cdot \|_1, \| \cdot \|_2, \| \cdot \|_\infty$ non-singular square J

Symmetric pos (semi)

definite

Suppose $A = A^*$, $x^* A x \geq 0 \quad \forall x \in \mathbb{C}^n$

$A = \underbrace{LU}_{L}$ breaks symmetry in A !

force L to be unit lower triangular

$$A \text{ SPD} \Rightarrow A = \begin{bmatrix} \alpha & v^* \\ v & C \end{bmatrix}_{n \times n}$$

$$\text{One step of LU} \Rightarrow \underbrace{\begin{bmatrix} 1 & \\ -\frac{1}{\alpha}v & I \end{bmatrix}}_{\text{elem. unit lower tri. matrix.}} A = \begin{bmatrix} \alpha & v^* \\ 0 & C - \frac{1}{\alpha}vv^* \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & \\ \frac{1}{\alpha}v & I \end{bmatrix} \begin{bmatrix} \alpha & v^* \\ 0 & C - \frac{1}{\alpha}vv^* \end{bmatrix}$$

$$= \begin{bmatrix} 1 & \\ \frac{1}{\alpha}v & I \end{bmatrix} \begin{bmatrix} 1 & \\ & C - \frac{1}{\alpha}vv^* \end{bmatrix} \begin{bmatrix} \alpha & v^* \\ 0 & I \end{bmatrix}$$

move α factor
of $\sqrt{\alpha}$ from right matrix
to left matrix

$$= \underbrace{\begin{bmatrix} \sqrt{\alpha} & 0 \\ \frac{1}{\sqrt{\alpha}}v & I \end{bmatrix}}_{R_1} \underbrace{\begin{bmatrix} 1 & \\ & C - \frac{1}{\alpha}vv^* \end{bmatrix}}_{A_1} \underbrace{\begin{bmatrix} \sqrt{\alpha} & \frac{1}{\sqrt{\alpha}}v^* \\ 0 & I \end{bmatrix}}_{R_1^*}$$

$$\text{Can "reverse"} \quad A = R_1 A_1 R_1^*$$

$$= R_1 \begin{bmatrix} 1 & \\ & C_1 \end{bmatrix} R_1^* = R_1 \begin{bmatrix} 1 & \\ & R_2 A_2 R_2^* \end{bmatrix} R_1^*$$

$$A = R_1 \underbrace{\left[\begin{array}{c|c} 1 & \\ \hline & R_2 \end{array} \right]}_{R_2} \left[\begin{array}{c|c} 1 & \\ \hline & A_3 \end{array} \right] \underbrace{\left[\begin{array}{c|c} 1 & \\ \hline & R_2^* \end{array} \right]}_{R_2^*} R_1^*$$

$$= R_1 R_2 \dots R_{n-1} R_{n-1}^* R_{n-2}^* \dots R_1^*$$

$$= R R^*, \quad R = \text{lower triangular}$$

Cholesky involves computing $C - \frac{1}{\alpha} w^*$
 where $\alpha = \text{top left diagonal entry of the submatrix at the } i\text{th step of Cholesky.}$

⇒ Ensure $\alpha \neq 0$!

1st step $A = \begin{bmatrix} \alpha & \vec{v}^* \\ \vec{v} & C \end{bmatrix}$

2nd step $A = \dots \left[\begin{array}{c|c} 1 & \\ \hline & C - \frac{1}{\alpha} w^* \end{array} \right] \dots$

next α is 1st diagonal entry of this.

Can prove $\alpha \neq 0$ at any step if $A = \text{SPD}$.

By induction: $X^* A X > 0$

(Base case) Let $X = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$, $X^* A X = \alpha > 0$

Induction) Show $C - \frac{1}{\alpha} w^*$ is still SPD

then Cholesky will never divide by zero.

Given $A = \begin{bmatrix} \alpha & v^* \\ v & C \end{bmatrix} = SPD$, can prove
 $C - \frac{1}{\alpha}vv^* = SPD$

$$u^*(C - \frac{1}{\alpha}vv^*)u > 0 \quad \forall u \in \mathbb{C}^{n-1}$$

But $x^*Ax > 0$: Let $x = \begin{bmatrix} \xi \\ y \end{bmatrix} \quad \xi \in \mathbb{C}, y \in \mathbb{C}^{n-1}$

$$x^*Ax = \begin{bmatrix} \xi \\ y \end{bmatrix} \begin{bmatrix} \alpha & v^* \\ v & C \end{bmatrix} \begin{bmatrix} \xi \\ y \end{bmatrix} = \alpha \xi \bar{\xi} + \bar{\xi} v^* y + \xi y^* v + y^* Cy > 0$$

$$\text{Let } \xi = \frac{-v^*y}{\alpha}$$

$$\begin{aligned} \Rightarrow x^*Ax &= \cancel{\alpha \frac{(v^*y)^2}{\alpha^2}} - \cancel{\frac{(v^*y)^2}{\alpha}} - \cancel{\frac{(v^*y)^2}{\alpha}} + y^* Cy \\ &= -\frac{1}{\alpha}(v^*y)^2 + y^* Cy \\ &= \underbrace{y^* Cy}_{\geq 0} - \frac{1}{\alpha} y^* v v^* y \\ &= y^* (C - \frac{1}{\alpha}vv^*) y > 0 \quad \forall y \in \mathbb{C}^{n-1} \end{aligned}$$

Advantages: cost & memory.

$$QR \approx \frac{4}{3}n^3$$

$$LU \approx \frac{2}{3}n^3$$

Cholesky $\approx \frac{1}{3}n^3$ w/ $\frac{1}{2}n(n+1)$ storage

vs n^2 storage

Cholesky doesn't require pivoting & is fairly numerically stable to roundoff.

If $A = \tilde{R}\tilde{R}^*$ under floating pt.

& $\tilde{R}\tilde{R}^*x = b$, then x solves

$$(A+E)x = b \quad w/ \frac{\|E\|}{\|A\|} \leq \epsilon_m C_n$$

Here, $C_n = a$ constant depending on n .

Suli & Meyers prove C_n doesn't grow as fast as in LU. C_n is similar to f for LU

but $R_{ik} \subset A_{ii}$ so C_n doesn't blow up like f does for LU.