

$$A_0 = A$$

for $i = 0, 1, 2, \dots$

$$\begin{cases} Q_k R_k = A_k \\ A_{k+1} = R_k Q_k \end{cases}$$

$$R_k = Q_k^* A_k$$

$$A_{k+1} = R_k Q_k = \underbrace{Q_k^* A_k Q_k}_{\text{preserve eigenvalues of } A.} \xrightarrow{\text{similarity transform } SAS^{-1}}$$

① Why does it work?

② How do you speed it up?

↳ reduce cost within each iter.

↳ accelerate QR iter for $O(1)$ iters.

QR iteration \Leftrightarrow block power iteration.

single vector) Given x_0 , $x_{k+1} = Ax_k$, $x_{k+1} = x_{k+1} / \|x_{k+1}\|$

Block) Given X_0 . $X_{k+1} = AX_k$, $X_{k+1} = \text{orthonormalize}(X_{k+1})$
 ↳ QR, or other

Simultaneous iteration

$$(X_{k+1}, R = \text{qr}(X_{k+1}))$$

Let $\tilde{Q}_0 = I$

for $k = 1, 2, \dots$

$$\begin{cases} Z = A \tilde{Q}_{k-1} \\ \tilde{Q}_k R_k = Z \end{cases} \quad (\text{normalization using QR})$$

\Rightarrow produces \tilde{Q}_k .

QR iteration

$$\text{Let } A_0 = A$$

for $k = 0, 1, 2, \dots$

$$\left[\begin{array}{l} Q_{k+1} R_{k+1} = A_k \\ A_{k+1} = R_{k+1} Q_{k+1} \end{array} \right] \quad A_k$$

Thm: $\tilde{Q}_k = Q_1 Q_2 \dots Q_k$

Define $\tilde{R}_k = R_k R_{k-1} \dots R_1$

then $SI \Leftrightarrow QR$ in the sense that

$$\textcircled{1} \quad A_k = \tilde{Q}_k^* A \tilde{Q}_k$$

$$\textcircled{2} \quad \tilde{Q}_k \tilde{R}_k = A^k$$

(Proof 82) For SI , $\tilde{Q}_k R_k = A \tilde{Q}_{k-1}$

Define $R_0 = I$, $Q_0 = I$. $AQ_0 = A = \tilde{Q}_1 R_1$

$$AA = A \tilde{Q}_1 R_1 = \tilde{Q}_2 R_2 R_1$$

$$A^3 = A(AA) = \underbrace{A \tilde{Q}_2 R_2 R_1}$$

$$= \tilde{Q}_3 R_3 R_2 R_1$$

$$A^4 = A(AAA) = A \tilde{Q}_3 R_3 R_2 R_1$$

$$= \tilde{Q}_4 R_4 R_3 R_2 R_1$$

$$A^k = \tilde{Q}_k R_k R_{k-1} \dots R_1$$

$$= \tilde{Q}_k \tilde{R}_k$$

(Proof of ①)

$$A_k = \underbrace{\tilde{Q}_k}_{\text{from QR}} \underbrace{A}_{\text{from SI}} \tilde{Q}_k$$

For QR $\Rightarrow A = Q_1 R_1$

$$A^2 = Q_1 R_1 Q_1 R_1$$

$$= Q_1 A_1 R_1$$

Recall $Q_2 R_2 = A_1 \longrightarrow$

$$\Rightarrow A^2 = Q_1 Q_2 R_2 R_1$$

$$= \tilde{Q}_2 \tilde{R}_2$$

$$A^k = \tilde{Q}_k \tilde{R}_k$$

$$\text{w/ } \tilde{Q}_k = Q_1 Q_2 \dots Q_k$$

$$\text{QR, SI} \iff A^k = \tilde{Q}_k \tilde{R}_k$$

can now show

$$A_k = \tilde{Q}_k \underbrace{A}_{\text{from SI}} \tilde{Q}_k$$

for QR $\Rightarrow A_k = R_k Q_k$

Since $Q_k R_k = A_{k-1} \Rightarrow R_k = Q_k^* A_{k-1}$

$\Rightarrow A_k = Q_k^* A_{k-1} Q_k$

$A_k = Q_k^* Q_{k-1}^* A_{k-2} Q_{k-1} Q_k$

$= Q_k^* Q_{k-1}^* Q_{k-2}^* A_{k-3} Q_{k-2} Q_{k-1} Q_k$

$A_k = \underbrace{Q_k^* Q_{k-1}^* \dots Q_1^*}_i A \underbrace{Q_1 \dots Q_k}$

$A_k = \tilde{Q}_k^* A \tilde{Q}_k$

\Rightarrow QR \Leftrightarrow SI equiv. in that they both produce matrices related to the QR fac. $q_1 A^k$.

Speeding up QR:

for $k = 1, 2, \dots, n$

$\left\{ \begin{array}{l} Q_k R_k = A_{k-1} \Rightarrow \text{compute QR factorization} \\ A_k = R_k Q_k \end{array} \right. = O(n^3)$

Idea: pre-factorize $A \Rightarrow$ Upper Hessenberg