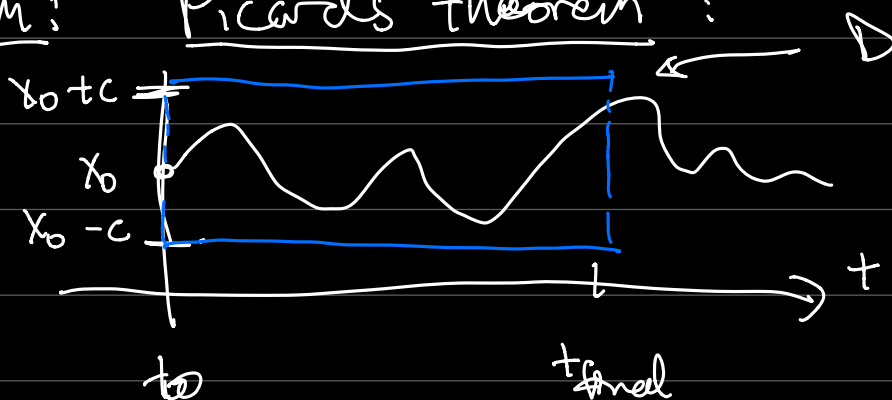


One-step methods: forward Euler, Improved Euler/Heun's method
backwards Euler, trapezoidal rule

$$x_{k+1} = x_k + h \varphi(x_k, t_k, h)$$

$$T_k = \frac{x(t_{k+1}) - x(t_k)}{h} - \varphi(x(t_k), t_k, h)$$

Thm: Picard's theorem:



$$\frac{dx(t)}{dt} = f(x, t)$$

Let $f(x, t)$ be continuous on $D = [x_0 - c, x_0 + c]$

① $x \in [t_0, t_{\text{final}}]$

for c which is fixed.

② Let $|f(x, t)| \leq k$ for $x, t \in D$

③ Assume Lipschitz continuity $\Rightarrow \exists L > 0$ s.t.
 $|f(u, t) - f(v, t)| \leq L|u - v| \quad \forall u, v \in [x_0 - c, x_0 + c]$
 $\forall t \in [t_0, t_{\text{final}}]$

④ Assume $C \geq \frac{k}{L} (e^{L(t_{\text{final}} - t_0)} - 1)$

depends on
 k, L

$\Rightarrow \exists! x \in C^1 [t_0, t_{\text{final}}]$ st.

$$x(0) = x_0 \quad \text{and} \quad \frac{dx}{dt} = f(x, t) \quad \text{on } [t_0, t_{\text{final}}]$$

$$\text{Furthermore, } |x(t) - x(0)| \leq C \\ \forall t \in [t_0, t_{\text{final}}]$$

Global error analysis: Assume $T_k \rightarrow 0$

as $h \rightarrow 0$ (necessary condition for convergence)

Def: a consistent method has $T_k \rightarrow 0$ as $h \rightarrow 0$

\hookrightarrow For any ϵ , $\exists h(\epsilon)$ st. $|T_k| < \epsilon$
for all $0 < h < h(\epsilon)$ and for
all $(x(t_k), t_k)$ and $(x(t_{k+1}), t_{k+1})$ on
 $[x_0 - C, x_0 + C] \times [t_0, t_{\text{final}}]$

$$x_{k+1} = x_k + h \varphi(x_k, t_k, h)$$

$$\text{Since } T_k = \frac{x(t_{k+1}) - x(t_k)}{h} - \varphi(x(t_k), t_k, h)$$

$$x(t_{k+1}) = x(t_k) + h \varphi(x(t_k), t_k, h) + h T_k$$

$$\underbrace{x(t_{k+1}) - x_{k+1}}_{e_{k+1}} = \underbrace{x(t_k) - x_k}_{e_k} + h (\varphi(x(t_k), t_k, h) - \varphi(x_k, t_k, h) + T_k)$$

Picard's: Lipschitz continuity on $f(x,t)$
 \Rightarrow assume similar conditions on φ .

$$|\varphi(u,t,h) - \varphi(v,t,h)| \leq L_{\varphi} |u-v|$$

$$\begin{aligned} |e_{k+1}| &\leq |e_k| + h (|\varphi(x(t_k), t_k, h) - \varphi(x_k, t_k, h)| + |\tau_k|) \\ &\leq |e_k| + h (L_{\varphi} |x(t_k) - x_k| + |\tau_k|) \\ &= |e_k| + h L_{\varphi} |e_k| + |\tau_k| \\ &= (1 + h L_{\varphi}) |e_k| + |\tau_k| \end{aligned}$$

max trunc.
error

Picard's: $|f(x,t)| \leq k \iff |\tau_k| \leq T$ for $0 \leq k \leq n$

$$|e_{k+1}| \leq (1 + h L_{\varphi}) |e_k| + T$$

$$|e_0| = 0 \quad (x(0) = x_0)$$

$$|e_1| = h |\tau_0| \leq hT$$

$$|e_2| = (1 + h L_{\varphi}) |e_1| + hT$$

$$\leq (1 + h L_{\varphi}) hT + hT$$

$$|e_3| \leq (1 + h L_{\varphi}) |e_2| + hT$$

$$\leq (1 + h L_{\varphi}) ((1 + h L_{\varphi}) hT + hT) + hT$$

$$\leq (1 + h L_{\varphi})^2 hT + (1 + h L_{\varphi}) hT + hT$$

$$|e_n| \leq hT \sum_{k=0}^{n-1} (1+hL\tau)^k \Rightarrow \text{geometric series}$$

$$= hT \frac{1 - (1+hL\tau)^n}{1 - (1+hL\tau)}$$

$$\sum_{k=0}^{n-1} r^k = \frac{1-r^n}{1-r}$$

$$= \frac{T}{L\tau} |1 - (1+hL\tau)^n|$$

$$e^{hL\tau} = \sum_{k=0}^{\infty} \frac{(hL\tau)^k}{k!} = 1 + hL\tau + \underbrace{\sum_{k=1}^{\infty} \frac{(hL\tau)^k}{k!}}_{\text{if } hL\tau \ll 1 \text{ then } \approx 0}$$

also positive since $h > 0$ ←

If $hL\tau \ll 1$, $|e_n| \leq \frac{T}{L\tau} |e^{nhL\tau} - 1|$

for equispaced time steps, $nh = T_{\text{final}}$ $\leq \frac{T}{L\tau} |e^{T_{\text{final}} L\tau} - 1|$

$$\Rightarrow |x(t_n) - x_n| \leq \frac{T}{L\tau} |e^{T_{\text{final}} L\tau} - 1|$$

Note $e^{T_{\text{final}} L\tau}$ bad, but in absolute sense.

Ex: $\frac{dx}{dt} = \lambda x \Rightarrow x(t_n) = x_0 e^{\lambda nh}$

$$x(t) = x_0 e^{\lambda t}$$