

$$\text{An } m\text{-step LMM : } \sum_{j=0}^m \alpha_j x_{k+j} = h \sum_{j=0}^m \beta_j f_{k+j} \quad \left| \frac{\partial x}{\partial t} = f(x, t) \right.$$

Last time: LMM truncation error $T_k \Rightarrow x'(t_k + jh)$

$$\left(\sum_{j=0}^m \beta_j \right) T_k = \underbrace{\sum_{j=0}^m \alpha_j \underbrace{x(t_k + jh)}_{x(t_{k+j})}}_{h \beta_j f(x_{k+j}, t_{k+j})}$$

$$(\sum \beta_j) T_k = \frac{1}{h} \left[\sum_{j=0}^m \alpha_j \right] x(t_k) \stackrel{\text{need } = 0 \text{ for } T_k \not\rightarrow \infty \text{ as } h \rightarrow 0}{=} \quad$$

$$+ \sum_{l=0}^{\infty} h^l \left(\sum_{j=0}^m \frac{\alpha_j j^{l+1}}{(l+1)!} - \beta_j \frac{j^l}{l!} \right) x^{(l+1)}(t_k)$$

$$= \frac{1}{h} \left[\sum_{j=0}^m \alpha_j \right] x(t_k) \rightarrow \text{Need } \sum_{j=0}^m \alpha_j = 0$$

$$+ \left[\sum_{j=0}^m (\alpha_j - \beta_j) \right] x'(t_k) \rightarrow \sum_{j=0}^m (\alpha_j - \beta_j) = 0$$

Consistency condition

$$+ h \sum_{j=0}^m \left(\frac{j^2}{2} \alpha_j - j \beta_j \right) x''(t_k)$$

$$+ h^2 \sum_{j=0}^m \left(\frac{j^3}{6} \alpha_j - \frac{j^2}{2} \beta_j \right) x'''(t_k)$$

$$+ h^3 \sum_{j=0}^m \left(\frac{j^4}{24} \alpha_j - \frac{j^3}{6} \beta_j \right) x^{(4)}(t_k) + \dots$$

Def: a consistent LMM has $T_K \rightarrow 0$ as $h \rightarrow 0$

Thm: A LMM is consistent iff

$$\sum_{j=0}^m \alpha_j = \sum_{j=0}^m j\alpha_j - \beta_0 = 0$$

Def: A LMM is has order of accuracy p if $T_K = O(h^p)$ as $h \rightarrow 0$

Thm: An m -step LMM is order $p > 1$ iff

① it is consistent

$$\sum_{j=0}^m \left(\frac{j^{l+1}}{(l+1)!} \alpha_j - \frac{j^l}{l!} \beta_j \right) = 0$$

for $l = 1, 2, \dots, p-1,$

$$\text{Ex: } \begin{pmatrix} \text{Ewd.} \\ \text{Euler} \end{pmatrix} x_{k+1} - x_k = h f_k \quad \begin{array}{ll} \alpha_0 = -1 & \beta_0 = 1 \\ \alpha_1 = 1 & \beta_1 = 0 \end{array}$$

$$\text{consistency} \quad \begin{cases} \sum \alpha_j = 0 \\ \sum (j\alpha_j - \beta_j) = \alpha_1 + \alpha_0 \cdot 0 - \beta_1 - \beta_0 \\ = 1 - 1 = 0 \end{cases} = 0$$

$$\text{Is it 2nd order? } \sum \frac{j^2}{2} \alpha_j - \frac{1}{2} \beta_j = \frac{1}{2} \alpha_1 - \beta_1 = \frac{1}{2} - 1 = -\frac{1}{2}$$

Ex: Trapezoidal rule

$$x_{k+1} - x_k = \frac{h}{2}(f_k + f_{k+1})$$

$$\begin{aligned}\alpha_0 &= -1 & \beta_0 &= \frac{1}{2} \\ \alpha_1 &= 1 & \beta_1 &= \frac{1}{2}\end{aligned}$$

consistency $\left\{ \begin{array}{l} \sum \alpha_j = 0 \\ \sum j\alpha_j - j\beta_j = \alpha_1 + 0\alpha_0 - \beta_1 - \beta_2 \\ \quad = 1 - \frac{1}{2} - \frac{1}{2} = 0 \end{array} \right.$

$$O(h^2) \quad \sum j^2 \alpha_j - j \beta_j = \frac{1}{2} \alpha_1 - 1 \beta_1 = \frac{1}{2} - \frac{1}{2} = 0$$

$$\text{Not } O(h^3) \quad \sum j^3 \alpha_j - j^2 \beta_j = \frac{1}{6} \alpha_1 - \frac{1}{2} \beta_1 = \frac{1}{6} - \frac{1}{2} \neq 0$$

Stability:

$$\textcircled{1} \quad x_{k+2} - \frac{3}{2}x_{k+1} + \frac{1}{2}x_k = \frac{h}{4}(5f_{k+1} - 3f_k)$$

$$\begin{aligned}\alpha_0 &= 1 & \beta_0 &= -\frac{3}{4} \\ \alpha_1 &= -\frac{3}{2} & \beta_1 &= \frac{5}{4} \\ \alpha_2 &= 1 & \beta_2 &= 0\end{aligned}$$

$$\textcircled{2} \quad x_{k+2} - 3x_{k+1} + 2x_k = \frac{h}{2}(f_{k+1} - 3f_k)$$

$$\begin{aligned}\alpha_0 &= 2 & \beta_0 &= -\frac{3}{2} \\ \alpha_1 &= -3 & \beta_1 &= \frac{1}{2} \\ \alpha_2 &= 1 & \beta_2 &= 0\end{aligned}$$

→ Both are consistent & 2nd order accurate.

Ex: $x'(t) = x(t) \Rightarrow x(t) = x(0)e^t$
Method 1 works, Method 2 blows up

$x'(t) = 0 \Rightarrow x(t) = x(0)$
Method 1 works, Method 2 blows up

use this to analyze an LMM

$$f(x, t) = 0 \Rightarrow f_k = 0$$

$$\Rightarrow \text{LMM is } f_{k+1} = \sum_{j=0}^m \alpha_j x_{k+j} = 0$$

\Rightarrow zero stable method doesn't admit $x_k \rightarrow \infty$ for $f_k = 0$